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ANALYSIS OF MONTE CARLO SIMULATIONS BASED ON DIFFERENT DISCRETIZATION SCHEMAS OF CONTINUOUS STOCHASTIC MODELS FROM FINANCE

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Abstract: In this paper we will compute with Monte Carlo simulations some derivative values at maturity time in some stochastic models with different discretization schemas (like Euler-Mayurana, Millstein, Runge-Kutta, generic Duffy) and compare results and computing efforts.

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1. BLACK-SCHOLES-MERTON MODEL AND BLACK-SCHOLES PDE

One of popular stochastic equation that models a traded asset (like a stock) is the *Black-Scholes-Merton model* based on *geometric brownian motion* (see [1]):

$$dS(t)=S(t)[\mu dt+\sigma dW(t)] \quad (1)$$

where $(S(t), t \geq 0)$ is the stochastic process for asset value at timestamp t , $(W(t), t \geq 0)$ is a *Wiener standard process* (see [2]), μ is the *drift rate of return* and σ is *volatility*.

A derivative based on this asset is an other traded asset that fructify at *maturity time* T , payoff depend on value of support, $S(T)$. *payoff* function is defined as:

$$\text{payoff}: \mathbb{R}_+ \rightarrow \mathbb{R} \quad (2)$$

Main problem is pricing of a financial derivative. For this, we build an risk-free portfolio based on some supports and some derivatives. After applying of Ito lemma (see [3]) we obtain Black-Scholes PDE (see [4]):

$$V_t + \frac{1}{2} \sigma^2 S^2 V_{SS} + rSV_S - rV = 0 \quad (3)$$

for pricing derivatives, where:

$$V: \mathbb{R}_+ \times [0, T] \rightarrow \mathbb{R}_+ \quad (4)$$

and $V(S, t)$ is value of derivatives at timestamp t if support is valued as S .

Note that for a generalized brownian motion:

$$dS(t)=A(S(t), t)dt+B(S(t), t)dW(t) \quad (5)$$

where $A(S, t)$ and $B(S, t)$ are some algebraic expression, we can build a generalized form of Black-Scholes PDE (see [5]):

$$V_t + \frac{1}{2} B^2 V_{SS} + rSV_S - rV = 0 \quad (6)$$

Black-Scholes PDE and generalized Black-Scholes PDE can be linked with Dirichlet condition:

$$V(0,t) = 0 \quad (7)$$

$$V(S,T) = \text{payoff}(S) \quad (8)$$

that means for 0 value of support, derivatives is valued to 0 too, and value at maturity is payoff function.

2. OTHER MODELS

We give some usual stochastic models in table 1 (see [5]):

Name	Equations
<i>Bachelier</i> (see [12])	$dS = adt + bdW$
<i>Black-Scholes-Merton</i>	$dS/S = adt + bdW$
<i>CEV</i> (see [13])	$dS = aSdt + bS^\beta dW$
<i>Chen</i> (see [11])	$dS = (\theta(t) - \alpha(t))dt + S^{1/2}\sigma(t)dW$ $d\alpha = (\zeta(t) - \alpha(t))dt + \alpha(t)^{1/2}\sigma(t)dW$ $d\sigma = (\beta(t) - \sigma(t))dt + \sigma(t)^{1/2}\eta(t)dW$
<i>Dias-Rocha</i> (see [6], p. 68)	$dS/S = [k_1(\mu - S) - \lambda k_2]dt + \sigma dW(t) + dq$ $\text{Prob}(dq = 0) = 1 - \lambda dt$ $\text{Prob}(dq = \varphi) = \lambda dt$
<i>Double-Heston</i> (see [7], [8])	$dS = \mu Sdt + v_1^{1/2} S dW_{11}(t) + v_2^{1/2} S dW_{12}(t)$ $dv_1 = k_1(\theta_1 - v_1)dt + \xi_1 v_1^{1/2} dW_1(t)$ $dv_2 = k_2(\theta_2 - v_2)dt + \xi_2 v_2^{1/2} dW_2(t)$ $dW_1 dW_{12} = r_1 dt$ $dW_2 dW_{22} = r_2 dt$
<i>Heston</i> (see [9])	$dS = \mu Sdt + v^{1/2} S dW_1(t)$ $dv = k(\theta - v)dt + \xi v^{1/2} dW_2(t)$ $dW_1 dW_2 = dt$
<i>Marlim</i> (see [6], p. 68)	$dS = k(\mu - S)dt + \sigma dW(t) + dq$ $\text{Prob}(dq = 0) = 1 - \lambda dt$ $\text{Prob}(dq = \varphi) = \lambda dt$
<i>Merton</i> (diffusion+jumps, see [10], p. 585)	$dS/S = (a - \lambda b)dt + \sigma dW(t) + dq$ $\text{Prob}(dq = 0) = 1 - \lambda dt$ $\text{Prob}(dq = \varphi) = \lambda dt$
<i>SABR</i> (see [14])	$dS = vS^\beta dW_1(t)$ $dv = \alpha v dW_2(t)$ $dW_1 dW_2 = r dt$
<i>Vasicek</i>	$dS = a(b - S)dt + cdW(t)$

Table 1. Some usual stochastic models.

3. DISCRETIZATION SCHEMAS

For a stochastic process $X(t)_{t \geq 0}$ with next SDE:

$$dX(t) = A(X(t), t)dt + B(X(t), t)dW(t) \quad (9)$$

where $W(t)_{t \geq 0}$ is a standard Wiener process, than we can approximate process $X(t)_{t \geq 0}$ with a Markov chain $(Y_n)_{n \geq 0}$, where Y_n is $X(t_n)$. Some usual discretization methods can be found in table 2 (see [5]):

Method name	Schema
<i>Explicit Euler-Maruyana (Euler)</i>	$Y_{n+1} = Y_n + A(Y_n, t_n)\Delta + B(Y_n, t_n)N_n\sqrt{\Delta}$



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Method name	Schema
<i>method</i> (see [15])	
<i>Implicit Euler-Maruyana (Euler) method</i> (see [15])	$Y_{n+1} = Y_n + A(Y_{n+1}, t_n)\Delta + B(Y_n, t_n)N_n\sqrt{\Delta}$
<i>θ-stochastic implicit Euler-Maruyana method</i>	$Y_{n+1} = Y_n + A(\theta_n Y_{n+1} + (1-\theta_n)Y_n, t_n + \theta_n\Delta)\Delta + B(Y_n, t_n)N_n\sqrt{\Delta}$
<i>Implicit median point method</i> (see [15])	$Y_{n+1} = Y_n + A((Y_n + Y_{n+1})/2, (t_n + t_{n+1})/2)\Delta + B(Y_n, t_n)N_n\sqrt{\Delta}$
<i>Implicit trapezoidal method</i> (see [15])	$Y_{n+1} = Y_n + (A(Y_{n+1}, t_{n+1}) + A(Y_n, t_n))\Delta/2 + B(Y_n, t_n)N_n\sqrt{\Delta}$
<i>Millstein method</i> (see [16])	$Y_{n+1} = Y_n + A(Y_n, t_n)\Delta + B(Y_n, t_n)\sqrt{\Delta}N_n + 1/2B(Y_n, t_n)B_X(Y_n, t_n)\Delta(N_n^2 - 1)$
<i>A method like Runge-Kutta</i> (see [16])	$Y_{n+1} = Y_n + A(Y_n, t_n)\Delta + B(Y_n, t_n)\sqrt{\Delta}N_n + 1/2(B(Y_n + A(Y_n, t_n)\Delta + B(Y_n, t_n)\sqrt{\Delta}, t_n) - B(Y_n, t_n))\sqrt{\Delta}(N_n^2 - 1)$
<i>Generic Duffy method</i> (see [16])	$Y_{n+1} = Y_n + [\alpha C(Y_{n+1}, t_{n+1}) + (1-\alpha)C(Y_n, t_n)]\Delta + [\eta B(Y_{n+1}, t_{n+1}) + (1-\eta)B(Y_n, t_n)]\sqrt{\Delta}N_n$ $C(Y, t) = A(Y, t) - \eta B(Y, t)B_X(Y, t)$
<i>Extended Duffy method</i> (see [16])	$Y_{n+1} = Y_n + [\alpha C(Y_{n+1}, t_{n+1}) + (1-\alpha)C(Y_n, t_n)]\Delta + [\eta B(Y_{n+1}, t_{n+1}) + (1-\eta)B(Y_n, t_n)]\sqrt{\Delta}N_n + [\xi A(Y_{n+1}, t_{n+1})C(Y_{n+1}, t_{n+1}) + (1+\xi)A(Y_n, t_n)C(Y_n, t_n)]\Delta$ $C(Y, t) = A(Y, t) - \eta B(Y, t)B_X(Y, t)$

Table 2. Some usual discretization schema.

where:

- $\Delta = t_{n+1} - t_n$;
- N_n is $\sim N(0, 1)$;
- θ_n is a stochastic value in $(0, 1)$;
- α is a parameter in $(0, 1)$;
- η is a parameter in $(0, 1)$;
- ξ is a parameter in $(0, 1)$;
- B_X is partial derivative of B on nontemporal dimension.

Note that for a static B (like volatility parameter in Bachelier model) we will have:

$$B_X = 0 \quad (10)$$

Note that for a static A (like drift parameter in Bachelier model) we will have an equivalence between all of explicit and implicit Euler-Maruyana schemas. If A and B are statically, Millstein schema is equivalent too.

If we have a stochastic model with multiple SDEs (like Chen, Heston, double-Heston etc), then we can build a multidimensional Markov Chain: for each SDE we can use any discretization schema like in previous paragraph.

4. NUMERICAL SIMULATIONS

For Bachelier and Black-Scholes-Merton model with:

a = 1
b = 4%
S0 = 9
Payoff(S)=max {0,S-10}
T = 1
Δ =0.01

with Monte Carlo simulation on N=10, 100 and 1000 simulation steps we obtain:

	Pricing value for Bachelier model	Pricing value for Black-Scholes-Merton model	Monte Carlo iterations
<i>Explicit Euler-Maruyana (Euler)</i>	0.00631039	14.1453	10
	0.019516	14.4509	100
	0.0221323	14.5943	1000
<i>Millstein method</i>	0.0287962	14.4454	10
	0.0253927	14.7503	100
	0.0219063	14.6148	1000
<i>Generic Duffy method</i>	0.0168662	13.7366	10
	0.0189815	14.2445	100
	0.0203399	14.2373	1000

Scilab (see [16]) program for this simulation is:

```
function
f=NextValue(CurrentValue,tip,a,b,delta)
N=rand(0,'normal');
radical=sqrt(delta);
patrat=N*N;
// tip>0 Bachelier
// Explicit Euler-Maruyana (Euler)
if tip==1 then
f=CurrentValue+a*delta+b*N*radical;
// Millstein method
elseif tip==2 then
f=CurrentValue+a*delta+b*radical*N;
// A method like Runge-Kutta
elseif tip==3 then
f=CurrentValue+a*delta+b*radical*N+(b-
b*radical*(patrat-1))/2;
// Generic Duffy method
elseif tip==4 then
f=CurrentValue+a*delta+b*radical*N;
```

```
// tip<0 Black-Scholes-Merton
// Explicit Euler-Maruyana (Euler)
elseif tip==-1 then
f=CurrentValue*(1+a*delta+b*N*radical);
// Millstein method
elseif tip==-2 then
f=CurrentValue*(1+a*delta+b*radical*N+b*
delta*(patrat-1)/2);
// A method like Runge-Kutta
elseif tip==-3 then
f=CurrentValue*(1+a*delta+b*radical*N+(b
*(1+a*delta+b*radical)-b*radical*(patrat-1))/2;
// Generic Duffy method  $\hat{I}\pm=\hat{I}=1/2$ 
elseif tip==-4 then
f=CurrentValue*(1+(a-
b/2)*delta/2+b*radical*N/2)/(-b*radical*N/2-(a-
b/2)*delta/2+1);
end
endfunction

function
f=Path(FirstValue,Maturity,Exercise,tip,a,b,delta)
x=FirstValue;
for t=0:delta:Maturity,
x=NextValue(x,tip,a,b,delta); end;
f=max(0,x-Exercise);
endfunction

function
f=CompleteSimulation(N,FirstValue,Maturity,Exercise,tip,a,b,delta)
s=0;
for i=1:N,
s=s+Path(FirstValue,Maturity,Exercise,tip,a,b
,delta);
end;
f=s/N;
endfunction

S0=9;
T=1;
Ex=10;
a=1;
b=0.04;
delta=0.01;
for tip=1:4,
printf("%d %g %g\n",tip, CompleteSimulation(
10, S0, T, Ex, tip, a, b ,
delta), CompleteSimulation( 10, S0, T, Ex, -tip,
a, b , delta));
printf("%d %g %g\n",tip, CompleteSimulation(
100, S0, T, Ex, tip, a, b ,
delta), CompleteSimulation( 100, S0, T, Ex, -
tip, a, b , delta));
```



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```
printf("%d      %g      %g\n",tip,
CompleteSimulation(1000, S0, T, Ex, tip, a, b ,
delta), CompleteSimulation(1000, S0, T, Ex, -
tip, a, b , delta));
end;
```

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